

DISTANCE-PRESERVING GRAPH CONTRACTIONS

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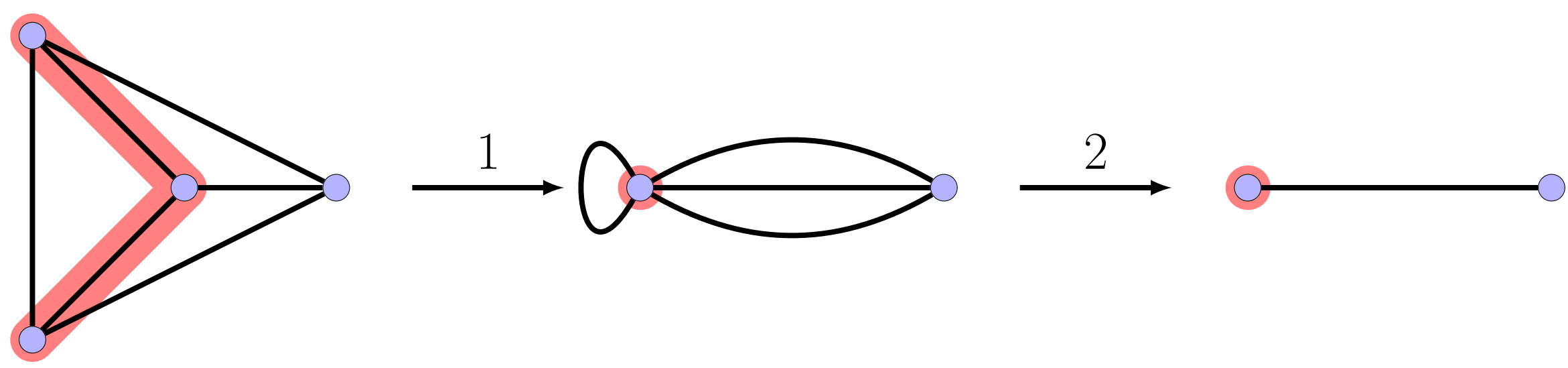
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Setting

Given: A simple, undirected graph $G = (V, E)$ with edge lengths $\ell : E \rightarrow \mathbb{R}_{>0}$ and error parameters $\alpha \geq 1$ (multiplicative), $\beta \geq 0$ (additive).

Operation: Edge contractions, i.e. given a set $C \subseteq E$ we obtain the graph G/C by:

- contracting the edges in C and
- deleting parallel edges and loops ($\Delta(C) :=$ set of deleted edges).



The number of vertices and edges in G/C coincides with

- the number of conn. comp. of (V, C) and
- $m(G) - |C| - |\Delta(C)|$, respectively.

Distance preservation: We don't want distances in G/C to decrease too much, thus we call $C \subseteq E$ an (α, β) -contraction if

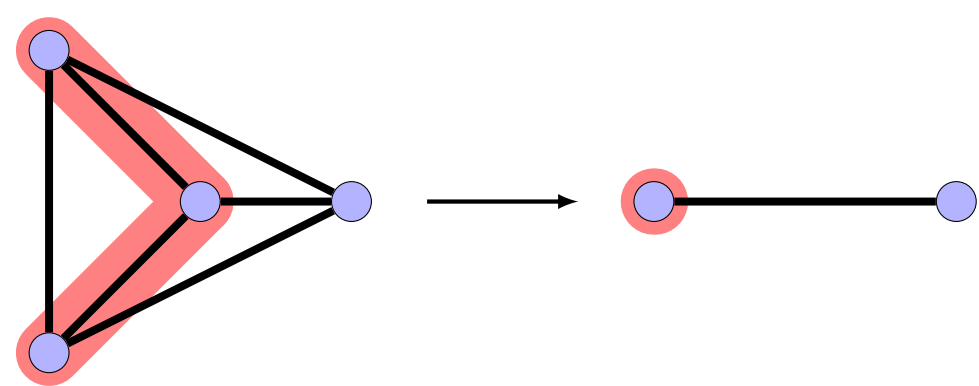
$$\text{dist}_{G/C}(u, v) \geq \text{dist}_G(u, v) / \alpha - \beta.$$

Goal: Find an (α, β) -contraction C with the maximum number $|C \cup \Delta(C)|$ of lost edges.

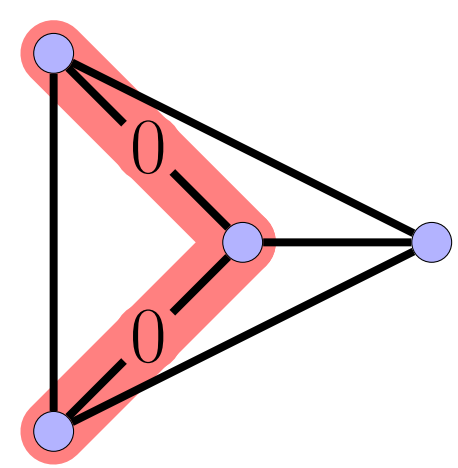
A different view and comparison to spanners

Contractions:

Contraction of edges in C :



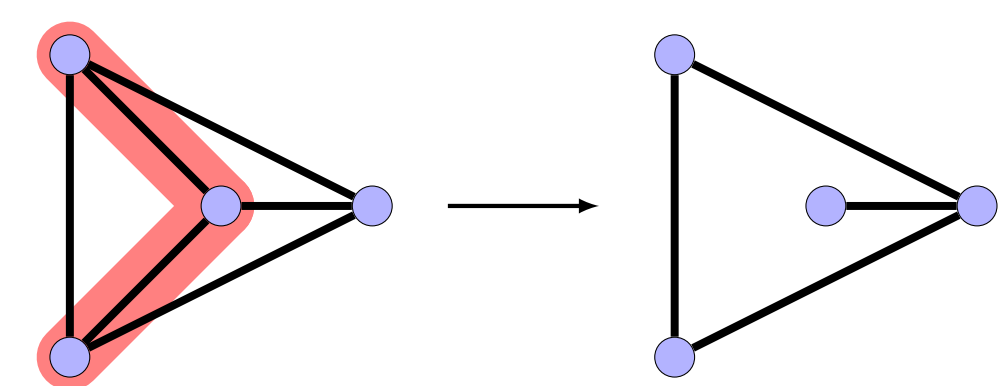
Equivalent to setting edge lengths in C to 0:



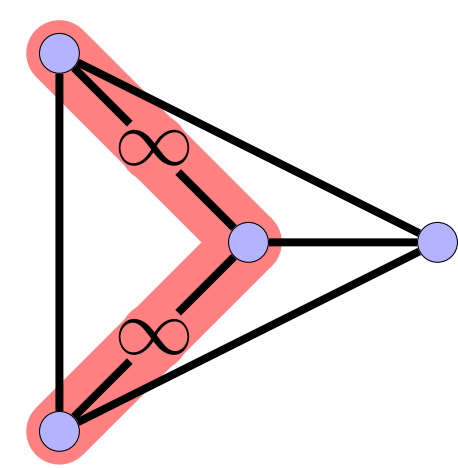
$$\text{dist}_0(u, v) \geq \text{dist}_G(u, v) / \alpha - \beta$$

Spanners:

Deletion of edges in $E \setminus E'$:



Equivalent to setting edge lengths in $E \setminus E'$ to ∞ :

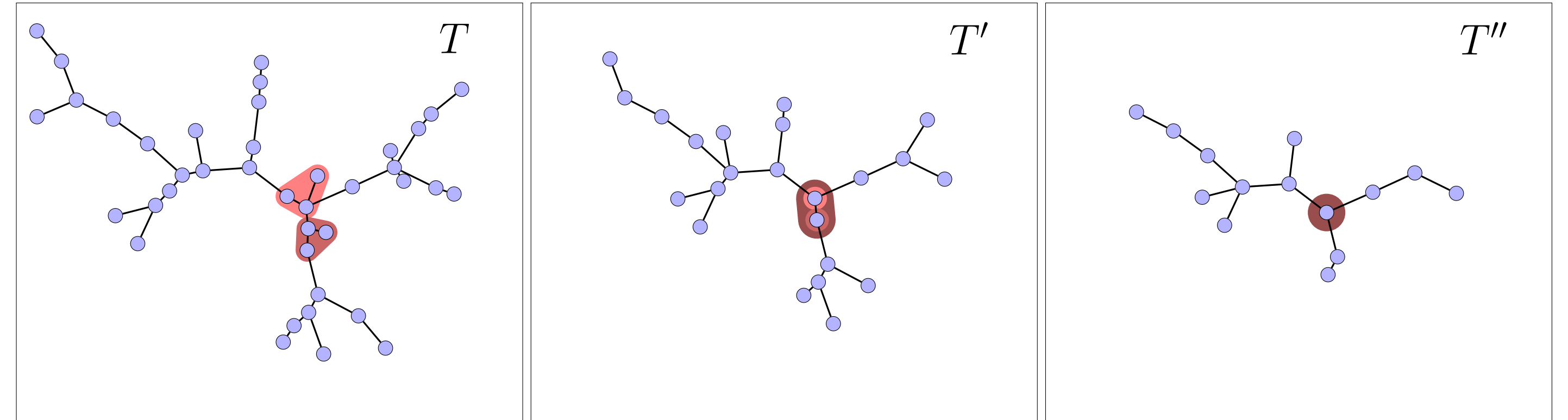


$$\text{dist}_\infty(u, v) \leq \alpha \text{dist}_G(u, v) + \beta$$

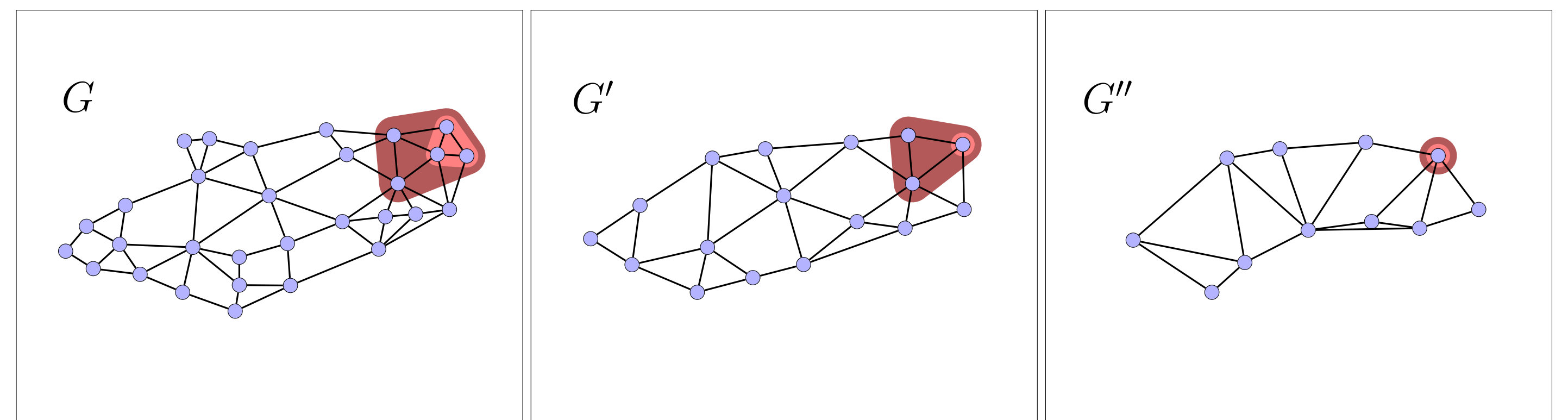
Reminder: Spanner
A subgraph $H = (V, E')$, $E' \subseteq E$ is an (α, β) -spanner of G if $\text{dist}_H(u, v) \leq \alpha \text{dist}_G(u, v) + \beta$.

Examples of Iterative Contractions

Two iterations with $\alpha = 5/4$ and $\beta = 3$ on a tree:



Two iterations with $\alpha = 4/3$ and $\beta = 3$ on a planar graph:



Distances are geometric and some contracted sets of vertices are highlighted.

Results

Algorithms and hardness

Greedy Algorithms	Graph classes			
	Path	Tree	Cycle	General
addit. ($\alpha=1$), unit lg.	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$m^{\frac{1}{2}-\epsilon}$ -inapx.
affine (α, β), unit lg.				
addit. ($\alpha=1$)			NP-hard	$n^{1-\epsilon}$ -inapx
affine (α, β)	$\mathcal{O}(n^3)$			

Even for bipartite graphs and $\beta = 1$

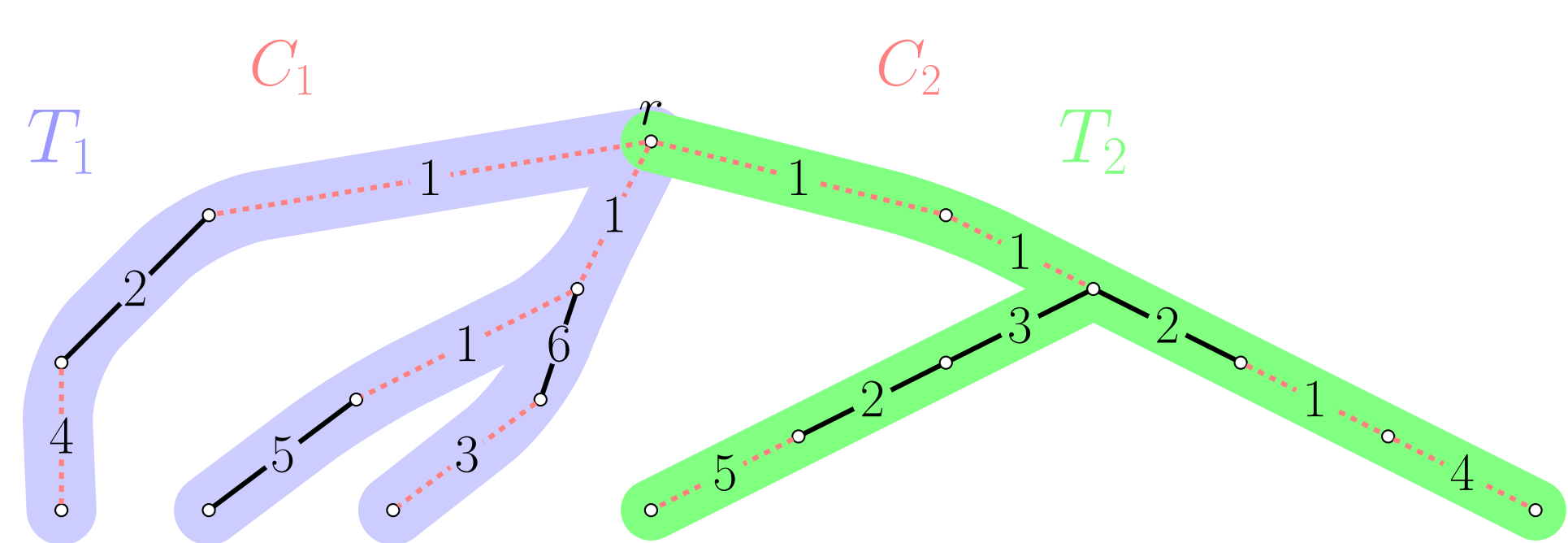
Dynamic Programming (see below)

Asymptotic bounds with unit lengths

	# of edges in G/C	Time
$(\alpha, \beta) = (2k - 1, 1)$	$n^{1+1/k}$	$\mathcal{O}(m)$
$(\alpha, \beta) = (2 \log_2 n - 1, 1)$	$2n$	$\mathcal{O}(m)$
$(\alpha, \beta) = (k - 1, 1)$	$\Omega(n^{1+1/k})$	—
$(\alpha, \beta) = (1, k)$	$m - km/(2n)$	$\mathcal{O}(m)$
$(\alpha, \beta) = (1, k)$	$\mathcal{O}(n^2/k)$	$\mathcal{O}(m)$
$(\alpha, \beta) = (1, \mathcal{O}(1))$	$\Omega(n^{4/3-o(1)})$ [Abboud, Bodwin '16]	—
min. degree D		Time
$(\alpha, \beta) = (5, 1)$	n/D	$\mathcal{O}(m)$
$(\alpha, \beta) = (k, 1)$	$\Omega(n/(kD))$	—

k-Partition (see below)
conditional on girth conjecture

Dynamic Programming on Trees



Split T at the root r .
If C_1, C_2 are feasible, when is $C := C_1 \cup C_2$?

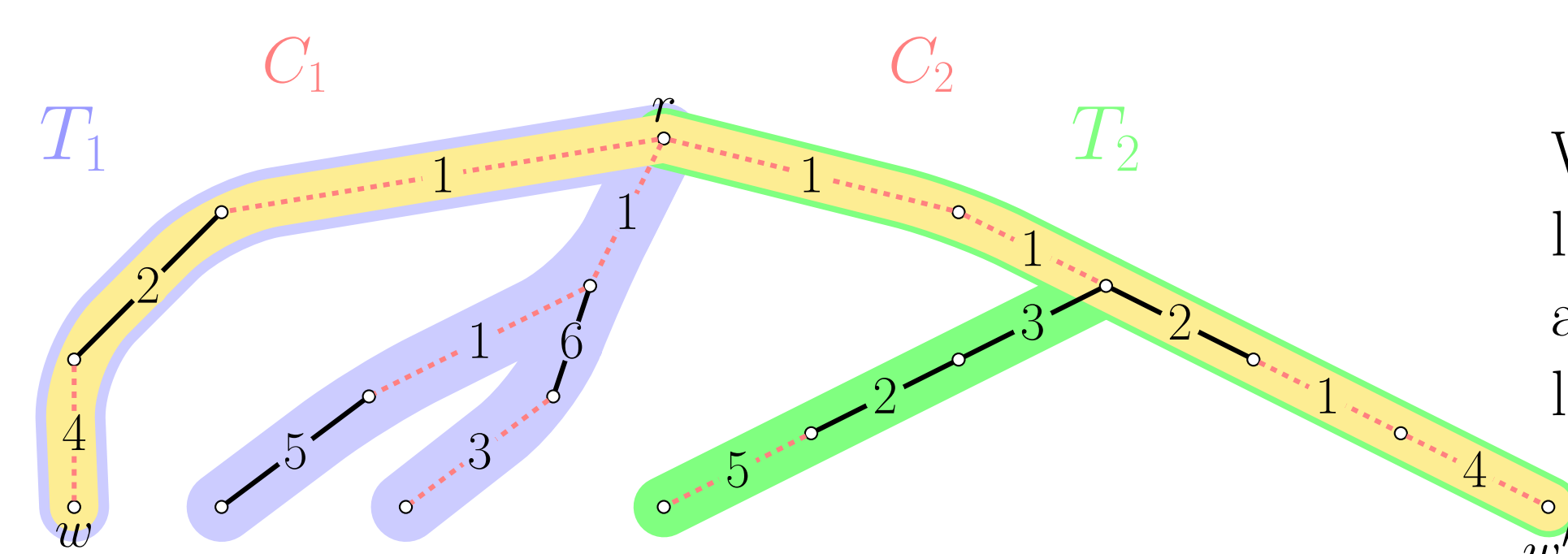
Key definition: $\text{load}(P) := \ell(P) / \alpha - \ell_{G/C}(P)$ for any path P

Properties:

- Feasibility $\Leftrightarrow \text{load}(P) \leq \beta$ for all P
- Additivity: $\text{load}(P_1) + \text{load}(P_2) = \text{load}(P_1 + P_2)$

Define $\text{load}(T, v) := \max\{\text{load}(P) : P \text{ ends in } v\}$

Lemma: C feasible $\Leftrightarrow C_1, C_2$ feasible and $\text{load}(T_1, r) + \text{load}(T_2, r) \leq \beta$



With $\alpha = 2$,
 $\text{load}(T_1, r) = \text{load}(w, r) = 1.5$
and
 $\text{load}(T_2, r) = \text{load}(w', r) = 2.5$.

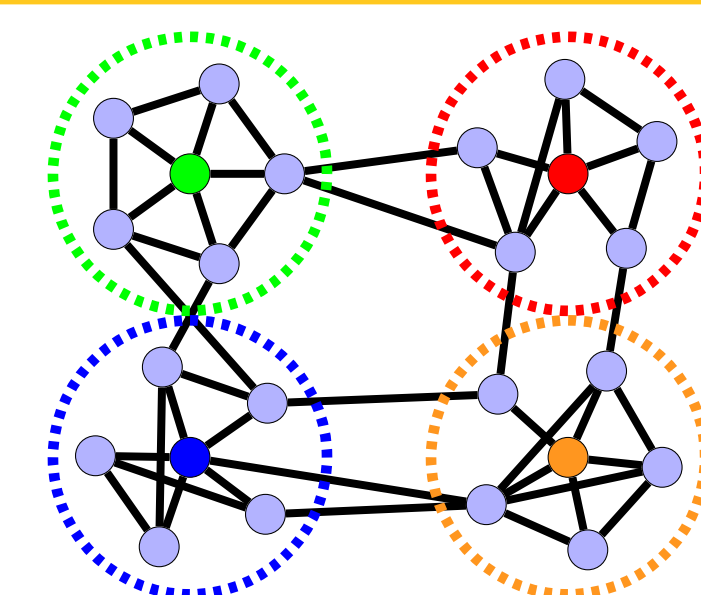
Lemma $\Rightarrow C$ feasible if $\beta \geq 4$

Bottom-up dynamic programming finds solutions of all possible sizes minimizing their respective loads, in $\mathcal{O}(n^3)$ time.

Asymptotic Bounds

Small (α, β) -contractions in unweighted graphs can be constructed similarly to spanners:

k-Partition



Example of $k = 2$ -partition P with:

- $P = \{(\bullet, P_1), (\bullet, P_2), (\bullet, P_3), (\bullet, P_4)\}$
- vertices have distance at most $1 = k - 1$ to their respective centers
- 'few' intra cluster edges [Awerbuch '85]

Contractions:

$(2k - 1, 1)$ -contraction with at most $n^{1+1/k}$ edges

Spanners:

$(2k - 1, 0)$ -spanner with at most $\mathcal{O}(n^{1+1/k})$ edges [Baswana et al. '12]